Study of Weak Basis Invariants, Hierarchy Limit, and Effective Theory in the Universal Seesaw Model

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in collaboration with

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(on going work)

- Introduction
- The model
- Weak-basis invariants
- WL-WR mixing, mass eigenvalue, and mixing angle
- Hierarchy limit
- Summary

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Introduction

- Standard Model (SM) is most successful theory incorporate the dynamics of sub-atomic particle $v \approx 246 \text{ GeV}$
- However, SM cannot explain e.g. quark mass hierarchy

$$m_i = \frac{y_i v}{\sqrt{2}}; \quad i = u, d, c, s, t, b$$

• Universal seesaw model \rightarrow smallness of up quark mass explained by the tiny ratio of $SU(2)_R$ breaking and SU(2) singlet vector-like quark (VLQ) mass M_U

$$m_u = \frac{y_{uR}v_Ry_{uL}v}{2M_U} = \frac{y_uv}{\sqrt{2}} \to y_u = \frac{y_{uR}v_Ry_{uL}}{\sqrt{2}M_U}$$

Quark mass (PDG)	Yukawa coupling
$m_u = 2.16 \text{ MeV}$	$y_u \simeq 1.24 \times 10^{-5}$
$m_d = 4.67 \text{ MeV}$	$y_d \simeq 2.68 \times 10^{-5}$
$m_s = 93.4 \text{ MeV}$	$y_s \simeq 5.37 \times 10^{-4}$
$m_c = 1.27 \text{ GeV}$	$y_c \simeq 7.30 \times 10^{-3}$
$m_b = 4.18 \text{ GeV}$	$y_b \simeq 0.024$
$m_t = 172.69 \text{ GeV}$	$y_t \simeq 0.99$

$$m_u, m_d, m_s$$
 from $\overline{\mathrm{MS}}$ at $\mu = 2~\mathrm{GeV}$

 m_c, m_b from $\overline{\mathrm{MS}}$ at $\mu = \overline{m}$

 m_t from direct measurement

A. Davidson, K.C. Wali (1987); S. Rajpoot (1987); T. Morozumi, T. Satou, M. N. Rebelo, M. Tanimoto (1997) Y. Kiyo, T. Morozumi, P Parada, M. N. Rebelo, M Tanimoto (1999)

Introduction

- Physical observables are basis-independent
- In quark sector, one have freedom to rephase the quark fields \rightarrow Redefinition of CKM matrix

 $V_{\alpha j}' = e^{-i\phi_{\alpha}} V_{\alpha j} e^{i\phi_j}$

- Example of CKM rephasing invariants \rightarrow CP-odd Jarlskog invariant $J = \text{Im}(V_{11}V_{22}V_{12}^*V_{21}^*)$
- Flavor matrices (Yukawa matrices) are basis-dependent \rightarrow weak-basis transformation
- Our purpose:
 - obtain the weak-basis invariants quantities
 - mass eigenvalue, mixing matrix at some hierarchy limit

One generation case of Quark sector of universal seesaw model

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The model[T. Morozumi, A.S. Adam, Y. Kawamura, A.H.P, Y. Shimizu, K. Yamamoto arXiv:2211.02360]

We study the quark sector of the universal seesaw model with $SU(2)_L \times SU(2)_R \times U(1)_{Y'}$

$$\begin{array}{ll} \text{Particle content:} \quad \psi_{L}^{i} = \begin{pmatrix} u^{i} \\ d^{i} \end{pmatrix}_{L} : (\mathbf{2}, 1, 1/6) & \psi_{R}^{i} = \begin{pmatrix} u^{i} \\ d^{i} \end{pmatrix}_{R} : (1, \mathbf{2}, 1/6) & i = 1, 2, 3; I = 1, 2, 3 \\ \hline Q = I_{3_{L}} + I_{3_{R}} + Y' \\ \psi_{L} = \begin{pmatrix} \phi_{L}^{+} \\ \phi_{L}^{0} \end{pmatrix} : (\mathbf{2}, 1, 1/2) & \phi_{R} = \begin{pmatrix} \phi_{R}^{+} \\ \phi_{R}^{0} \end{pmatrix} : (1, \mathbf{2}, 1/2) & \langle \phi_{R} \rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ v_{L} \end{pmatrix} \\ \langle \phi_{R} \rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ v_{R} \end{pmatrix} \\ \langle \phi_{R} \rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ v_{R} \end{pmatrix} \end{array}$$

The Lagrangian of the model,

$$\mathcal{L}_{\text{Doublets}} = \sum_{i=1}^{3} \overline{\psi_{Li}} \left(i \not\partial - g_L \notW_L - g_1 \frac{1}{6} \notB_1 \right) \psi_{Li} + \sum_{i=1}^{3} \overline{\psi_{Ri}} \left(i \not\partial - g_R \notW_R - g_1 \frac{1}{6} \notB_1 \right) \psi_{Ri}$$
$$\mathcal{L}_{\text{VLQ}} = \sum_{I=1}^{3} \overline{U_I} \left(i \not\partial - g_1 \notB_1 \frac{2}{3} - M_{U_I} \right) U_I + \sum_{I=1}^{3} \overline{D_I} \left(i \not\partial + g_1 \notB_1 \frac{1}{3} - M_{D_I} \right) D_I$$

 $\mathcal{L}_{\text{VLQ-Doublets}} = -y_{LiJ}^{u} \overline{\psi_{iL}} \tilde{\phi}_{L} U_{J} - y_{RiJ}^{u} \overline{\psi_{iR}} \tilde{\phi}_{R} U_{J} - y_{LiJ}^{d} \overline{\psi_{iL}} \phi_{L} D_{J} - y_{RiJ}^{d} \overline{\psi_{iR}} \phi_{R} D_{J} - h.c.$

The model

Mass hierarchy:



We will study the one generation case

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The lagrangian of the model:

$$\mathcal{L} = -\overline{\psi_L} m_{uL} U - \overline{\psi_R} m_{uR} U - \overline{\psi_L} m_{dL} D - \overline{\psi_R} m_{dR} D - (h.c.) - \overline{U_L} M_U U_R - \overline{D_L} M_D D_R - (h.c.)$$

$$m_{uL} = \frac{y_{uL}v_L}{\sqrt{2}} \qquad m_{dL} = \frac{y_{dL}v_L}{\sqrt{2}}$$
$$m_{uR} = \frac{y_{uR}v_R}{\sqrt{2}} \qquad m_{dR} = \frac{y_{dR}v_R}{\sqrt{2}}$$

Define following weak-basis transformation (WBT) on doublet quarks and VL quarks in this model as follow,

$$\psi'_L = e^{i\theta_{V_L}}\psi_L, \qquad \psi'_R = e^{i\theta_{V_R}}\psi_R, \qquad U' = e^{i\theta_U}U, \qquad D' = e^{i\theta_D}L$$

The Lagrangian will unchanged if the quark and VLQ mass have to transform as,

 $m'_{uL} = e^{i(\theta_{V_L} - \theta_U)} m_{uL}, \qquad m'_{uR} = e^{i(\theta_{V_R} - \theta_U)} m_{uR}, \qquad m'_{dL} = e^{i(\theta_{V_L} - \theta_D)} m_{dL}, \qquad m'_{dR} = e^{i(\theta_{V_R} - \theta_D)} m_{dR},$ $M'_U = M_U, \qquad M'_D = M_D$

Denoting:

$$z_{1} = e^{i\theta_{V_{L}}}, z_{2} = e^{i\theta_{V_{R}}}, z_{3} = e^{i\theta_{U}}, z_{4} = e^{i\theta_{D}}$$

$$q_{1} = m_{uL}, q_{2} = m_{uL}^{*}, q_{3} = m_{uR}, q_{4} = m_{uR}^{*}, q_{5} = m_{dL}, q_{6} = m_{dL}^{*}, q_{7} = m_{dR}, q_{8} = m_{dR}^{*}, q_{9} = M_{U}, q_{10} = M_{D}$$

Weak-basis invariants

Using Molien-Weyl formula see e.g. [Y. Wang, B. Yu, S. Zhou (2021)]

$$\mathcal{H}(q_1,\ldots,q_N) = \int [d\mu]_G \prod_{i=1}^N \frac{1}{\det(1-q_i R_i(g))}$$

 $\mathcal{H}(q_1,\ldots,q_N)$: multigraded Hilbert-series q_i : arbitrary complex number with $|q_i| < 1$ $R_i(q)$: representation of group G where $q \in G$

Haar measure: $\int [d\mu]_G = \frac{1}{(2\pi i)^4} \oint_{|z_1|=1} \frac{dz_1}{z_1} \oint_{|z_2|=1} \frac{dz_2}{z_2} \oint_{|z_2|=1} \frac{dz_3}{z_3} \oint_{|z_4|=1} \frac{dz_4}{z_4}$ ex: $[\det(1-q_1z_1z_3^{-1})]^{-1}$

We obtain the multigraded Hilbert series:

$$\mathcal{H}(q_1,\ldots,q_{10}) = \frac{1 - q_1 q_2 q_3 q_4 q_5 q_6 q_7 q_8}{(1 - q_1 q_2)(1 - q_3 q_4)(1 - q_5 q_6)(1 - q_7 q_8)(1 - q_1 q_4 q_6 q_7)(1 - q_2 q_3 q_5 q_8)(1 - q_9)(1 - q_{10})}$$
asic WBIs:

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$$I_{1} = m_{uL}^{2}, \quad I_{2} = m_{uR}^{2}, \quad I_{3} = m_{dL}^{2}, \quad I_{4} = m_{dR}^{2}, \quad I_{5} = m_{uL}m_{uR}^{*}m_{dL}^{*}m_{dR}, \quad I_{6} = m_{uL}^{*}m_{uR}m_{dL}m_{dR}^{*}$$
$$I_{7} = M_{U}, \quad I_{8} = M_{D}$$

 $I_5 I_6 = I_1 I_2 I_3 I_4$ There is one relation among the basic WBIs

Weak-basis invariants

By changing $q_1, \ldots, q_{10} \rightarrow q$, we obtain the ungraded Hilbert series:

$$H(q) = \frac{1+q^4}{(1-q)^2(1-q^2)^4(1-q^4)}$$

7 independent WBIs

- CP even $\rightarrow I_1, I_2, I_3, I_4, I_7, I_8$
- CP odd $\rightarrow J_9 \equiv I_5 I_6$

CP violating WBI:

$$W = \text{Im}(m_{uL}m_{uR}^*m_{dL}^*m_{dR}) = \frac{J_9}{2i}$$

Next: Finding the source of this CP violating WBI

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WB freedom:

$$\begin{aligned} m'_{uL} &= e^{i(\theta_{V_L} - \theta_U)} m_{uL} \\ \theta_{V_L} - \theta_U &= -\arg(m_{uR}) \\ \theta_{V_R} - \theta_U &= -\arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{dL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{uL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{uL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{uL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{uL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{uL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{uL}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{uR}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{uR}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uL}) - \arg(m_{uR}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uR}) + \arg(m_{uR}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uR}) + \arg(m_{uR}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uR}) + \arg(m_{uR}) \\ \theta_{V_R} - \theta_D &= -\arg(m_{uR}) + \arg(m_{uR}) + \arg(m_{uR}$$

. . .

Lagrangian with the new weak basis:

$$\mathcal{L} = -\overline{\psi_L} m_{uL} U - \overline{\psi_R} m_{uR} U - \overline{\psi_L} m_{dL} D - \overline{\psi_R} m_{dR} e^{i\theta_{WI}} D - \overline{U_L} M_U U_R - \overline{D_L} M_D D_R - h.c.$$

m' = |m|

Separate the up-type and down-type:

$$\mathcal{L}_{u} = -\left(\begin{array}{ccc}\overline{u_{L}} & \overline{U_{L}}\end{array}\right) \left(\begin{array}{ccc}0 & m_{uL}\\m_{uR} & M_{U}\end{array}\right) \left(\begin{array}{ccc}u_{R}\\U_{R}\end{array}\right) - \left(\begin{array}{ccc}\overline{u_{R}} & \overline{U_{R}}\end{array}\right) \left(\begin{array}{ccc}0 & m_{uR}\\m_{uL} & M_{U}\end{array}\right) \left(\begin{array}{ccc}u_{L}\\U_{L}\end{array}\right)$$
$$\underbrace{\mathcal{M}_{u}}^{T}$$
$$\mathcal{L}_{d} = -\left(\begin{array}{ccc}\overline{d_{L}} & \overline{D_{L}}\end{array}\right) \left(\begin{array}{ccc}0 & m_{dL}\\m_{dR}e^{-i\theta_{WI}} & M_{D}\end{array}\right) \left(\begin{array}{ccc}d_{R}\\D_{R}\end{array}\right) - \left(\begin{array}{ccc}\overline{d_{R}} & \overline{D_{R}}\end{array}\right) \left(\begin{array}{ccc}0 & m_{dR}e^{i\theta_{WI}}\\m_{dL} & M_{D}\end{array}\right) \left(\begin{array}{ccc}d_{L}\\D_{L}\end{array}\right)$$
Flavor basis \rightarrow mass basis

$$\mathcal{L}_{u} = -\left(\begin{array}{cc} \overline{u_{L}'} & \overline{U_{L}'} \end{array}\right) V_{U_{L}}^{\dagger} \left(\begin{array}{cc} 0 & m_{uL} \\ m_{uR} & M_{U} \end{array}\right) V_{U_{R}} \left(\begin{array}{c} u_{R}' \\ U_{R}' \end{array}\right) - h.c.$$

$$(\begin{array}{c} m_{u_{1}} & 0 \\ 0 & m_{u_{2}} \end{array})$$

$$\mathcal{L}_{d} = -\left(\begin{array}{c} \overline{d_{L}'} & \overline{D_{L}'} \end{array}\right) V_{D_{L}}^{\dagger} \left(\begin{array}{c} 0 & m_{dL} \\ m_{dR}e^{-i\theta_{WI}} & M_{D} \end{array}\right) V_{D_{R}} \left(\begin{array}{c} d_{R}' \\ D_{R}' \end{array}\right) - h.c.$$

$$(\begin{array}{c} m_{d_{1}} & 0 \\ 0 & m_{d_{2}} \end{array})$$
diagonalize

$$\begin{pmatrix} u_L \\ U_L \end{pmatrix} = V_{U_L} \begin{pmatrix} u'_L \\ U'_L \end{pmatrix}$$
$$\begin{pmatrix} u_R \\ U_R \end{pmatrix} = V_{U_R} \begin{pmatrix} u'_R \\ U'_R \end{pmatrix}$$
$$\begin{pmatrix} d_L \\ D_L \end{pmatrix} = V_{D_L} \begin{pmatrix} d'_L \\ D'_L \end{pmatrix}$$
$$\begin{pmatrix} d_R \\ D_R \end{pmatrix} = V_{D_R} \begin{pmatrix} d'_R \\ D'_R \end{pmatrix}$$

 $V_{U_L}, V_{U_R}, V_{D_L}, V_{D_R}$ are 2 x 2 unitary matrices

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 $2\sqrt{2}$

$$\begin{aligned} \mathcal{L}_{CC} &= -\frac{g_L}{\sqrt{2}} (\bar{u}_L \gamma^{\mu} d_L W^+_{\mu L} + \bar{d}_L \gamma^{\mu} u_L W^-_{\mu L}) - \frac{g_R}{\sqrt{2}} (\bar{u}_R \gamma^{\mu} d_R W^+_{\mu R} + \bar{d}_R \gamma^{\mu} u_R W^-_{\mu R}) \\ &= -\frac{g_L}{2\sqrt{2}} \left(\bar{u}'_i V^*_{U_{L1i}} V_{D_{L1j}} \gamma^{\mu} (1 - \gamma^5) d'_j W^+_{\mu L} + \bar{d}'_i V^*_{D_{L1i}} V_{U_{L1j}} \gamma^{\mu} (1 - \gamma^5) u'_j W^-_{\mu L} \right) \\ &- \frac{g_R}{2\sqrt{2}} \left(\bar{u}'_i V^*_{U_{R1i}} V_{D_{R1j}} \gamma^{\mu} (1 + \gamma^5) d'_j W^+_{\mu R} + \bar{d}'_i V^*_{D_{R1i}} V_{U_{R1j}} \gamma^{\mu} (1 + \gamma^5) u'_j W^-_{\mu R} \right) \end{aligned}$$

$$d_{L} = \sum_{j=1}^{2} V_{D_{L1j}} d'_{Lj}$$
$$\bar{u}_{L} = \sum_{i=1}^{2} V^{*}_{U_{L1i}} u'_{Li}$$
$$V^{\text{CKM}}_{L_{ij}} = V^{*}_{U_{L1i}} V_{D_{L1j}}$$

 $\Pi_{W_L W_R}^{\mu\nu}(0) = \frac{g_L g_R}{16\pi^2} (V_{U_{L11}}^* m_{u_1} V_{U_{R11}}) (V_{D_{L11}} m_{d_1} V_{D_{R11}}^*) g_{\mu\nu} [f(m_{u_1}, m_{d_1}) + f(m_{u_2}, m_{d_2}) - f(m_{u_1}, m_{d_2}) - f(m_{u_2}, m_{d_1})]$

Diagonalization of up-type quark and VLQ mass matrix

 $\begin{pmatrix} u_L \\ U_L \end{pmatrix} = \begin{pmatrix} \cos\theta_{U_l} & -\sin\theta_{U_l} \\ \sin\theta_{U_l} & \cos\theta_{U_l} \end{pmatrix} \begin{pmatrix} \cos\theta_{U_R} & \sin\theta_{U_R} \\ -\sin\theta_{U_R} & \cos\theta_{U_R} \end{pmatrix} \begin{pmatrix} u'_L \\ U'_L \end{pmatrix} \begin{pmatrix} u_R \\ U_R \end{pmatrix} = \begin{pmatrix} \cos\theta_{U_R} & \sin\theta_{U_R} \\ -\sin\theta_{U_R} & \cos\theta_{U_R} \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} u'_R \\ U'_R \end{pmatrix}$ Lagrangian of up-type mixing become: $\mathcal{L}_u = -\left(\begin{array}{c} \overline{u'_L} & \overline{U'_L} \end{array}\right) \begin{pmatrix} \cos\theta_{U_R} & -\sin\theta_{U_R} \\ \sin\theta_{U_R} & \cos\theta_{U_R} \end{array}\right) \begin{pmatrix} \cos\theta_{U_l} & \sin\theta_{U_l} \\ -\sin\theta_{U_l} & \cos\theta_{U_l} \end{array}\right) \begin{pmatrix} 0 & m_{u_L} \\ m_{u_R} & M_U \end{array}\right) \begin{pmatrix} \cos\theta_{U_R} & \sin\theta_{U_R} \\ -\sin\theta_{U_R} & \cos\theta_{U_R} \end{array}\right) \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} u'_R \\ U'_R \end{pmatrix}$ $= -\left(\begin{array}{c} \overline{u'_L} & \overline{U'_L} \end{array}\right) \begin{pmatrix} \cos\theta_{U_L} & -\sin\theta_{U_L} \\ \sin\theta_{U_L} & \cos\theta_{U_L} \end{array}\right) \begin{pmatrix} 0 & m_{u_L} \\ m_{u_R} & M_U \end{pmatrix} \begin{pmatrix} -\cos\theta_{U_R} & \sin\theta_{U_R} \\ \sin\theta_{U_R} & \cos\theta_{U_R} \end{pmatrix} \begin{pmatrix} u'_R \\ U'_R \end{pmatrix}$ $= -\left(\begin{array}{c} \overline{u'_L} & \overline{U'_L} \end{array}\right) \begin{pmatrix} m_{u_1} & 0 \\ 0 & m_{u_L} \\ 0 & m_{u_R} \end{pmatrix} \begin{pmatrix} u'_R \\ U'_R \end{pmatrix}$

Mass eigenvalue:

$$m_{u_1} = -\frac{\sqrt{M_U^2 + (m_{u_R} - m_{u_L})^2}}{2} + \frac{\sqrt{M_U^2 + (m_{u_R} + m_{u_L})^2}}{2}$$
$$m_{u_2} = \frac{\sqrt{M_U^2 + (m_{u_R} - m_{u_L})^2}}{2} + \frac{\sqrt{M_U^2 + (m_{u_R} + m_{u_L})^2}}{2}$$

Mixing angle:

$$\theta_{U_L} = \theta_{U_R} - \theta_{U_l}$$
$$\tan \theta_{U_l} = \frac{m_{u_R} - m_{u_L}}{M_U}$$
$$\tan 2\theta_{U_R} = \frac{2M_U m_{u_R}}{M_U^2 + m_{u_L}^2 - m_{u_R}^2}$$

Diagonalization of down-type quark and VLQ mass matrix

$$\begin{pmatrix} d_L \\ D_L \end{pmatrix} = \begin{pmatrix} \cos\theta_{D_l} & -\sin\theta_{D_l} \\ \sin\theta_{D_l} & \cos\theta_{D_l} \end{pmatrix} \begin{pmatrix} \cos\theta_{D_R} & \sin\theta_{D_R} \\ -\sin\theta_{D_R} & \cos\theta_{D_R} \end{pmatrix} \begin{pmatrix} d'_L \\ D'_L \end{pmatrix}$$

$$\begin{pmatrix} d_R \\ D_R \end{pmatrix} = \begin{pmatrix} e^{i\theta_{WI}} & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \cos\theta_{D_R} & \sin\theta_{D_R} \\ -\sin\theta_{D_R} & \cos\theta_{D_R} \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} d'_R \\ D'_R \end{pmatrix}$$

Lagrangian of down-type mixing become:

$$\mathcal{L}_{d} = -\left(\begin{array}{cc}\overline{d'_{L}} & \overline{D'_{L}}\end{array}\right) \left(\begin{array}{cc}\cos\theta_{D_{L}} & -\sin\theta_{D_{L}}\\\sin\theta_{D_{L}} & \cos\theta_{D_{L}}\end{array}\right) \left(\begin{array}{cc}0 & m_{d_{L}}\\m_{d_{R}}e^{-i\theta_{WI}} & M_{D}\end{array}\right) \left(\begin{array}{cc}-e^{i\theta_{WI}}\cos\theta_{D_{R}} & e^{i\theta_{WI}}\sin\theta_{D_{R}}\\\sin\theta_{D_{R}} & \cos\theta_{D_{R}}\end{array}\right) \left(\begin{array}{cc}d'_{R}\\D'_{R}\end{array}\right)$$
$$= -\left(\begin{array}{cc}\overline{d'_{L}} & \overline{D'_{L}}\end{array}\right) \left(\begin{array}{cc}m_{d_{1}} & 0\\0 & m_{d_{2}}\end{array}\right) \left(\begin{array}{cc}d'_{R}\\D'_{R}\end{array}\right)$$

Mass eigenvalue:

$$m_{d_1} = -\frac{\sqrt{M_D^2 + (m_{d_R} - m_{d_L})^2}}{2} + \frac{\sqrt{M_D^2 + (m_{d_R} + m_{d_L})^2}}{2}$$
$$m_{d_2} = \frac{\sqrt{M_D^2 + (m_{d_R} - m_{d_L})^2}}{2} + \frac{\sqrt{M_D^2 + (m_{d_R} + m_{d_L})^2}}{2}$$

Mixing angle:

$$\theta_{D_L} = \theta_{D_R} - \theta_{D_l}$$
$$\tan \theta_{D_l} = \frac{m_{d_R} - m_{d_L}}{M_D}$$
$$\tan 2\theta_{D_R} = \frac{2M_D m_{d_R}}{M_D^2 + m_{d_L}^2 - m_{d_R}^2}$$

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$$\begin{split} M_{U}, M_{D} \gg v_{R} \gg v_{L} & \begin{pmatrix} \cos \theta_{U_{L}} & -\sin \theta_{U_{L}} \\ \sin \theta_{U_{L}} & \cos \theta_{U_{L}} \end{pmatrix} \begin{pmatrix} 0 & m_{u_{L}} \\ m_{u_{R}} & M_{U} \end{pmatrix} \begin{pmatrix} -\cos \theta_{U_{R}} & \sin \theta_{U_{R}} \\ \sin \theta_{U_{R}} & \cos \theta_{U_{R}} \end{pmatrix} = \begin{pmatrix} m_{u_{1}} & 0 \\ 0 & m_{u_{2}} \end{pmatrix} \\ \begin{pmatrix} \cos \theta_{D_{L}} & -\sin \theta_{D_{L}} \\ \sin \theta_{D_{L}} & \cos \theta_{D_{L}} \end{pmatrix} \begin{pmatrix} 0 & m_{d_{L}} \\ m_{d_{R}}e^{-i\theta_{W1}} & M_{D} \end{pmatrix} \begin{pmatrix} -e^{i\theta_{W1}}\cos \theta_{D_{R}} & e^{i\theta_{W1}}\sin \theta_{D_{R}} \\ \sin \theta_{D_{R}} & \cos \theta_{D_{R}} \end{pmatrix} = \begin{pmatrix} m_{d_{1}} & 0 \\ 0 & m_{d_{2}} \end{pmatrix} \\ \begin{pmatrix} m_{u_{1}} & \frac{m_{u_{R}}m_{u_{L}}}{M_{U}} & = \frac{v_{R}y_{u}Ry_{u}v_{L}v_{L}}{2M_{U}} \end{pmatrix} \begin{bmatrix} m_{u_{2}} \simeq M_{U} \\ m_{d_{2}} \simeq M_{U} \end{bmatrix} \\ \hline m_{d_{1}} \simeq \frac{m_{d_{R}}m_{d_{L}}}{M_{D}} & = \frac{v_{R}y_{d}Ry_{d}Lv_{L}}{2M_{D}} \end{bmatrix} \begin{bmatrix} m_{u_{2}} \simeq M_{U} \\ m_{d_{2}} \simeq M_{D} \end{bmatrix} \\ \hline \text{Recall:} \\ W = \operatorname{Im}(m_{uL}m_{u_{R}}^{*}m_{d_{L}}^{*}m_{d_{R}}) = m_{uL}m_{uR}m_{dL}m_{dR}\operatorname{Im}(e^{i\theta_{W1}}) \end{split}$$

$$\Pi_{W_L W_R}^{\mu\nu}(0) = \frac{g_L g_R}{16\pi^2} (V_{U_{L11}}^* m_{u_1} V_{U_{R11}}) (V_{D_{L11}} m_{d_1} V_{D_{R11}}) g_{\mu\nu} [f(m_{u_1}, m_{d_1}) + f(m_{u_2}, m_{d_2}) - f(m_{u_1}, m_{d_2}) - f(m_{u_2}, m_{d_1})]$$

$$\operatorname{Im}\left(\Pi_{W_L W_R}^{\mu\nu}(0)\right) = \operatorname{Im}\left(\frac{m_{uL}m_{uR}m_{dL}m_{dR}}{M_U M_D}e^{-i\theta_{WI}}\right) = -\frac{W}{M_U M_D}$$

 $M_U, M_D \gg v_R \gg v_L$

This hierarchy limit is applied for:

1st generation quark

2nd generation quark

$$m_c \simeq \frac{m_{c_R} m_{c_L}}{M_C} = \frac{v_R y_{cR} y_{cL} v_L}{2M_C} \qquad m_{c'} \simeq M_C$$
$$m_s \simeq \frac{m_{s_R} m_{s_L}}{M_S} = \frac{v_R y_{sR} y_{sL} v_L}{2M_S} \qquad m_{s'} \simeq M_S$$

$M_U, M_D \gg v_R \gg v_L$

$$V_L^{\text{CKM}} = \begin{pmatrix} \cos \theta_{U_L} \cos \theta_{D_L} & \cos \theta_{U_L} \sin \theta_{D_L} \\ \sin \theta_{U_L} \cos \theta_{D_L} & \sin \theta_{U_L} \sin \theta_{D_L} \end{pmatrix} \simeq \begin{pmatrix} \simeq 1 & \frac{m_{dL}}{M_D} \\ \frac{m_{uL}}{M_U} & \frac{m_{uL}}{M_D} \frac{m_{dL}}{M_D} \end{pmatrix}$$

$$V_R^{\text{CKM}} = \begin{pmatrix} \cos\theta_{U_R}\cos\theta_{D_R} & \cos\theta_{U_R}\sin\theta_{D_R} \\ \sin\theta_{U_R}\cos\theta_{D_R} & \sin\theta_{U_R}\sin\theta_{D_R} \end{pmatrix} \begin{pmatrix} -e^{i\theta_{\text{WI}}} & 0 \\ 0 & e^{i\theta_{\text{WI}}} \end{pmatrix} \simeq \begin{pmatrix} \simeq 1 & \frac{m_{dR}}{M_D} \\ \frac{m_{uR}}{M_U} & \frac{m_{uR}}{M_U}\frac{m_{dR}}{M_D} \end{pmatrix} \begin{pmatrix} -e^{i\theta_{\text{WI}}} & 0 \\ 0 & e^{i\theta_{\text{WI}}} \end{pmatrix}$$

$$\mathcal{L}_{\rm CC} = -\frac{g_L}{\sqrt{2}} \left(\bar{u}'_{Li} V_{L_{ij}}^{\rm CKM} \gamma^{\mu} d'_{Lj} W_{\mu L}^{+} + h.c \right) - \frac{g_R}{\sqrt{2}} \left(\bar{u}'_{Ri} V_{R_{ij}}^{\rm CKM} \gamma^{\mu} d'_{Rj} W_{\mu R}^{+} + h.c. \right)$$

This hierarchy limit is applied for:

1st generation2nd generation $j_L^{\mu-} = \bar{u}_L \gamma^{\mu} d_L + \frac{m_{dL}}{M_D} \bar{u}_L \gamma^{\mu} d'_L + \frac{m_{uL}}{M_U} \bar{u}'_L \gamma^{\mu} d_L + \frac{m_{uL}}{M_U} \frac{m_{dL}}{M_D} \bar{u}'_L \gamma^{\mu} d'_L$ $j_L^{\mu-} = \bar{c}_L \gamma^{\mu} s_L + \frac{m_{sL}}{M_S} \bar{c}_L \gamma^{\mu} s'_L + \frac{m_{cL}}{M_C} \bar{c}'_L \gamma^{\mu} s_L + \frac{m_{cL}}{M_C} \frac{m_{sL}}{M_S} \bar{c}'_L \gamma^{\mu} s'_L$ $j_R^{\mu-} = \bar{u}_R \gamma^{\mu} d_R + \frac{m_{dR}}{M_D} \bar{u}_R \gamma^{\mu} d_R + \frac{m_{uR}}{M_U} \frac{m_{dR}}{M_D} \bar{u}'_R \gamma^{\mu} d_R$ $j_R^{\mu-} = \bar{c}_R \gamma^{\mu} s_R + \frac{m_{sR}}{M_S} \bar{c}_R \gamma^{\mu} s'_R + \frac{m_{cR}}{M_C} \bar{c}'_R \gamma^{\mu} s_R + \frac{m_{cR}}{M_C} \frac{m_{sR}}{M_S} \bar{c}'_R \gamma^{\mu} s'_R$

 $M_D \gg v_B \gg v_L$ $\begin{pmatrix} \cos\theta_{U_L} & -\sin\theta_{U_L} \\ \sin\theta_{U_L} & \cos\theta_{U_L} \end{pmatrix} \begin{pmatrix} 0 & m_{u_L} \\ m_{u_R} & M_U \end{pmatrix} \begin{pmatrix} -\cos\theta_{U_R} & \sin\theta_{U_R} \\ \sin\theta_{U_R} & \cos\theta_{U_R} \end{pmatrix} = \begin{pmatrix} m_{u_1} & 0 \\ 0 & m_{u_2} \end{pmatrix}$ $v_{B} > M_{U} \gg v_{L}$ $\begin{pmatrix} \cos\theta_{D_L} & -\sin\theta_{D_L} \\ \sin\theta_{D_L} & \cos\theta_{D_L} \end{pmatrix} \begin{pmatrix} 0 & m_{d_L} \\ m_{d_R}e^{-i\theta_{WI}} & M_D \end{pmatrix} \begin{pmatrix} -e^{i\theta_{WI}}\cos\theta_{D_R} & e^{i\theta_{WI}}\sin\theta_{D_R} \\ \sin\theta_{D_R} & \cos\theta_{D_R} \end{pmatrix} = \begin{pmatrix} m_{d_1} & 0 \\ 0 & m_{d_2} \end{pmatrix}$ Mass eigenvalues: Mixing angle: $m_{u_1} \simeq m_{uL}$ $m_{u_2} \simeq m_{uR}$ $\sin \theta_{U_L} \simeq \frac{M_U m_{uL}}{m_{uD}^2} \qquad \sin \theta_{D_L} \simeq \frac{m_{dL}}{M_D}$ $m_{d_1} \simeq \frac{m_{d_R} m_{d_L}}{M_D} = \frac{v_R y_{dR} y_{dL} v_L}{2M_D} \qquad \qquad m_{d_2} \simeq M_D$ $\sin \theta_{U_R} \simeq 1 \qquad \qquad \sin \theta_{D_R} \simeq \frac{m_{dR}}{M_D}$ $\cos \theta_{U_L} \simeq 1$ $\cos \theta_{D_L} = \cos \theta_{D_R} \simeq 1$ $\cos\theta_{U_R} \simeq \frac{M_U}{M_U}$ $\operatorname{Im}\left(\Pi_{W_L W_R}^{\mu\nu}(0)\right) = \operatorname{Im}\left(\frac{m_{uL}M_U m_{dL}m_{dR}}{m_{uR}M_D}e^{-i\theta_{WI}}\right) = -\frac{M_U W}{m_{\pi}^2 M_D}$

 $M_D \gg v_R \gg v_L$ $v_R > M_U \gg v_L$

This hierarchy limit applied for:

3rd generation quark

$$m_t \simeq m_{t_L} = \frac{y_{tL}v_L}{\sqrt{2}}$$

$$m_{t'} \simeq m_{t_R} = \frac{y_{tR}v_R}{\sqrt{2}}$$

$$m_b \simeq \frac{m_{b_R}m_{b_L}}{M_B} = \frac{v_R y_{bR} y_{bL} v_L}{2M_B}$$

$$m_{b'} \simeq M_B$$

 $M_D \gg v_R \gg v_L$ $v_R > M_U \gg v_L$

$$V_{L}^{\text{CKM}} = \begin{pmatrix} \cos\theta_{U_{L}}\cos\theta_{D_{L}} & \cos\theta_{U_{L}}\sin\theta_{D_{L}} \\ \sin\theta_{U_{L}}\cos\theta_{D_{L}} & \sin\theta_{U_{L}}\sin\theta_{D_{L}} \end{pmatrix} \simeq \begin{pmatrix} \simeq 1 & \frac{m_{dL}}{M_{D}} \\ \frac{M_{U}m_{uL}}{m_{uR}^{2}} & \frac{M_{U}m_{uL}}{m_{uR}^{2}} \frac{m_{dL}}{M_{D}} \end{pmatrix}$$
$$V_{R}^{\text{CKM}} = \begin{pmatrix} \cos\theta_{U_{R}}\cos\theta_{D_{R}} & \cos\theta_{U_{R}}\sin\theta_{D_{R}} \\ \sin\theta_{U_{R}}\cos\theta_{D_{R}} & \sin\theta_{U_{R}}\sin\theta_{D_{R}} \end{pmatrix} \begin{pmatrix} -e^{i\theta_{\text{WI}}} & 0 \\ 0 & e^{i\theta_{\text{WI}}} \end{pmatrix} \simeq \begin{pmatrix} \frac{M_{U}}{m_{uR}} & \frac{M_{U}}{m_{uR}} \frac{m_{dR}}{M_{D}} \\ \simeq 1 & \frac{m_{dR}}{M_{D}} \end{pmatrix} \begin{pmatrix} -e^{i\theta_{\text{WI}}} & 0 \\ 0 & e^{i\theta_{\text{WI}}} \end{pmatrix}$$

$$\mathcal{L}_{\rm CC} = -\frac{g_L}{\sqrt{2}} \left(\bar{u}'_{Li} V_{L_{ij}}^{\rm CKM} \gamma^{\mu} d'_{Lj} W^+_{\mu L} + h.c \right) - \frac{g_R}{\sqrt{2}} \left(\bar{u}'_{Ri} V_{R_{ij}}^{\rm CKM} \gamma^{\mu} d'_{Rj} W^+_{\mu R} + h.c. \right)$$

This hierarchy limit is applied for:

3rd generation quark

$$j_L^{\mu-} = \bar{t}_L \gamma^{\mu} b_L + \frac{m_{dL}}{M_D} \bar{t}_L \gamma^{\mu} b'_L + \frac{M_U m_{uL}}{m_{uR}^2} \bar{t}'_L \gamma^{\mu} b_L + \frac{M_U m_{uL}}{m_{uR}^2} \frac{m_{dL}}{M_D} \bar{t}'_L \gamma^{\mu} b'_L$$
$$j_R^{\mu-} = \frac{M_U}{m_{uR}} \bar{t}_R \gamma^{\mu} b_R + \frac{M_U}{m_{uR}} \frac{m_{dR}}{M_D} \bar{t}_R \gamma^{\mu} b'_R + \bar{t}'_R \gamma^{\mu} b_R + \frac{m_{dR}}{M_D} \bar{t}'_R \gamma^{\mu} b'_R$$

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Summary

- We study quark sector of universal seesaw model, in particular in one generation case
- There is one CP violating weak-basis invariant

$$W = \text{Im}(m_{uL}m_{uR}^*m_{dL}^*m_{dR}) = \frac{J_9}{2i}$$

which appears in the WL-WR mixing

- We have applied the hierarchy limit to the appropriate generation
- On going work: Effective theory → Integrated out down-type and up-type VLQ and obtained the dim 5 and 6 effective lagrangian

THANK YOU

BACKUP

Most BSM model, reduction to SM at low energies proceeds via decoupling of heavy
particles with masses of order Λ [B. Grzadkowski, M. Iskrzynski, M. Misiak, J. Rosiek (2010)]

$$\mathcal{L}_{\rm SM} = \mathcal{L}_{\rm SM}^{(4)} + \frac{1}{\Lambda} \sum_{i} C_i^{(5)} Q_i^{(5)} + \frac{1}{\Lambda^2} \sum_{i} C_i^{(6)} Q_i^{(6)} + \mathcal{O}\left(\frac{1}{\Lambda^3}\right)$$

Mass hierarchy (three generation case) :



Mass hierarchy (one generation case) :



Integrate out down-type VLQ at tree level



$$\mathcal{A}_{1} = \frac{y_{dR}y_{dL}^{*}}{M_{D}} \left(\bar{\psi}_{R}(x)\phi_{R}(x) \right) \left(\phi_{L}^{\dagger}(x)\psi_{L}(x) \right) \qquad \qquad \mathcal{L}_{\text{eff}}^{(5)} = C_{D}^{(5)}(\mu) \left(\bar{\psi}_{R}(x)\phi_{R}(x) \right) \left(\phi_{L}^{\dagger}(x)\psi_{L}(x) \right) + h.c.$$

$$C_D^{(5)}(M_D) = \frac{y_{dR}y_{dL}^*}{M_D}$$



Integrate out up-type VLQ at tree level



$$\mathcal{A}_3 = \frac{y_{uR}y_{uL}^*}{M_U} \left(\bar{\psi}_R(x)\tilde{\phi}_R(x) \right) \left(\tilde{\phi}_L^{\dagger}(x)\psi_L(x) \right)$$

$$\mathcal{L}_{\text{eff}}^{(5)} = C_U^{(5)}(\mu) \left(\bar{\psi}_R(x) \tilde{\phi}_R(x) \right) \left(\tilde{\phi}_L^{\dagger}(x) \psi_L(x) \right) + h.c.$$

$$C_U^{(5)}(M_U) = \frac{y_{uR}y_{uL}^*}{M_U}$$



Summary:

$$\mathcal{L}_{\text{eff}}^{(5)} = \frac{y_{dR} y_{dL}^*}{M_D} \left(\bar{\psi}_R(x) \phi_R(x) \right) \left(\phi_L^{\dagger}(x) \psi_L(x) \right) + h.c. + \frac{y_{uR} y_{uL}^*}{M_U} \left(\bar{\psi}_R(x) \tilde{\phi}_R(x) \right) \left(\tilde{\phi}_L^{\dagger}(x) \psi_L(x) \right) + h.c.$$

$$\mathcal{L}_{\text{eff}}^{(6)} = \frac{y_{dL} y_{dL}^*}{M_D^2} \left(\bar{\psi}_L(x) \phi_L(x) \right) i \not\!\!\!D_D \left(\phi_L^\dagger(x) \psi_L(x) \right) + (L \to R) + \frac{y_{uL} y_{uL}^*}{M_U^2} \left(\bar{\psi}_L(x) \tilde{\phi}_L(x) \right) i \not\!\!\!D_U \left(\tilde{\phi}_L^\dagger(x) \psi_L(x) \right) + (L \to R)$$